

## WET NGU P1 6-7D : Conjugate Gradient&Cosine-Squared 3.36 1D-gradient starting model :

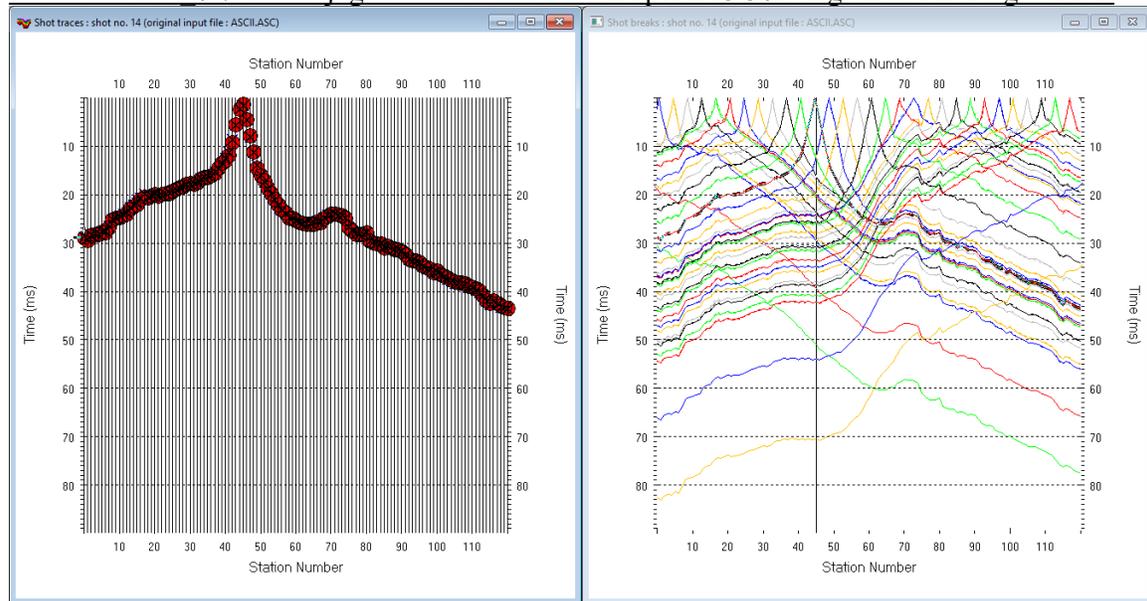


Fig. 1 : left : *Trace|Shot gather*, right : *Refractor|Shot breaks*. Shows fit between picked times (solid colored curves, red circles) and modeled times (dashed colored curves, blue crosses) obtained for 2D WET inversion output (Fig. 10)

To create the profile database, import the data and browse the imported shots do these steps :

- **File|New Profile...**, set *File name* to **P1\_6-7D** and click *Save button*
- in **Header|Profile...** set *Line type* to **Refraction spread/line**. Set *Station spacing* to 2.0 m.
- check box *Force grid cell size* and set *Cell size[m]* to 0.4m. See Fig. 2.
- unzip archive [P1\\_6-7D.zip](#) with files **1\_6-7DASCII.ASC**, **1\_6-7DCOORDS.COR**, **1\_6-7DSHOTS.SHO** & **P1\_6-7D.CLR** in directory **C:\RAY32\P1\_6-7D\INPUT**
- select **File|Import Data...** and set *Import data type* to **ASCII column format**. See Fig. 3.
- leave *Default spread type* at 10: **360 channels**
- click *Select button*, navigate into **C:\RAY32\P1\_6-7D\INPUT** and select file **P1\_6-7DASCII.ASC**
- set *Default sample count* to 900 to setup the y scale for *Trace|Shot gather* & *Refractor|Shot breaks*
- click **Import shots button** for batch import of all shots contained in **P1\_6-7DASCII.ASC**
- select **File|Update header data|Update Station Coordinates**
- navigate into directory **C:\RAY32\P1\_6-7D\INPUT**
- select file **1\_6-7DCOORDS.COR**. Click *Open button*.
- **File|Update header data|Update Shotpoint coordinates** with **1\_6-7DSHOTS.SHO**
- select **Trace|Shot gather** and **Window|Tile** to obtain Fig. 1

To configure and run Smooth inversion and display the 1D-Gradient starting model :

- uncheck **DeltatV|DeltatV Settings|Reduced offset 0.0 is valid trace with time 0.0**. See Fig. 13.
- check **DeltatV|DeltatV Settings|Suppress velocity artefacts**
- check **DeltatV|DeltatV Settings|Process every CMP offset**
- check **DeltatV|DeltatV Settings|Smooth CMP traveltimes**
- configure **Smooth invert|Smooth inversion Settings** as in Fig. 15
- select **Smooth invert|WET with 1D-gradient initial model** and confirm. Cancel WET continuation.
- select **Grid|Surfer plot Limits**. Click *Reset to grid*. Navigate into profile subdirectory **C:\RAY32\P1\_6-7D\GRADTOMO**. Click on file **GRADIENT.GRD** & click *Open*.
- check box **Plot limits active**. Set *Min. elevation* to 20m. Set *Max. elevation* to 72m. See Fig. 4.
- set *Min. velocity* to 500 m/s and *Max. velocity* to 6,000 m/s. Edit fields as in Fig. 4. Click *OK*.

- select *Grid|Image and contour velocity and coverage grids* & above `GRADIENT.GRD` to obtain Fig. 8
- *Grid|Image and contour velocity and coverage grids & ...\\model1\P1\_6-7\_2018m\_e4.grd* to get Fig. 9

To configure and run WET inversion and display 2D inversion output :

- check *WET Tomo|WET tomography Settings|Blank no coverage after last iteration.*
- uncheck *WET Tomo|WET tomography Settings|Blank below envelope after last iteration*
- check *WET Tomo|WET tomography Settings|Write|Store modeled picks after last iteration only*
- check *WET Tomo|WET tomography Settings|Scale wavepath width.* See Fig. 16.
- check *WET Tomo|WET tomography Settings|Scale WET filter height*
- check *WET Tomo|WET tomography Settings|Edit maximum valid WET velocity*
- in *WET Tomo|WET velocity update* set *a* to 0.5 and *b* to 10.0. Click *OK*. See Fig. 5.
- set *WET Tomo|Interactive WET tomography|Ricker differentiation* to -2 [Cosine-Squared]
- set *Min. velocity* to 10 m/s & *Max. velocity* to 6,000 m/s. See Fig. 6 (left).
- click radio button **Conjugate Gradient**
- set *CG iterations* (outer loop) to 7 and *Line Search iters.* (inner loop) to 2. See [Shewchuk 1994](#) .
- click button *Edit grid file generation* & set *Store each nth iteration only : n =* to 20. Click *OK*.
- click **Edit velocity smoothing**. Check **Manual specification of smoothing filter** . See Fig. 6 (right).
- set **Half smoothing filter width** to 2 columns & set **Half smoothing filter height** to 1 rows
- uncheck *Adapt shape of filter*. Set **Maximum velocity update** to 15% .
- set **Smooth nth iteration : n =** to 3
- leave **Uniform** button checked. Set **Uniform central row weight** to 100.
- leave **Damping** at default of 0.9 for *Conjugate-Gradient* method. Click *Accept parameters button*.
- click **Iterate** button & check **WET runs active**. Edit as in Fig. 7 and click **button OK**.
- click button **Start tomography processing** to obtain Fig. 10 & 12
- in Surfer 16 click on *menu View*. Check *Properties check box*.
- in Surfer 16 window for Fig. 10 click on *Custom colormap* button to right of *Colors label*. Click on *Load* button. Navigate into `C:\RAY32\P1_6-7D\INPUT` & select `P1_6-7D.CLR` . Click *Open&Apply&OK*.

Here some references to help file chapters and other relevant tutorials :

- for our **multiscale WET** inversion see updated [help file](#) chapter **WET tomography processing**
- our [SAGEEP11 tutorial](#) shows **Conjugate Gradient WET** inversion using 1D-gradient initial model for SAGEEP11 synthetic data forward-modeled over fault zone model
- our [twin tutorial](#) shows **Conjugate-gradient single-run WET inversion** using DeltatV+XTV pseudo-2D refraction starting model for same data as above (Fig. 1)
- [1\\_1D tutorial](#) shows multiscale **Conjugate-Gradient WET** inversion of [NGU profile 1\\_1D](#) data shown in Fig. 4.5.1 using DeltatV+XTV starting model
- our [2017 tutorial](#) shows **Steepest Descent WET** inversion using Plus-Minus layered refraction starting model for [NGU 2017](#) P1\_1 synthetic data
- [Ostrowski et al.](#) show fault zone imaging using our WET inversion and dense shot spacing

**Edit Profile**

Line ID: P1\_6-7D  
 Line type: Refraction spread/line  
 Job ID: NGU synthetic data 2018

Instrument: \_\_\_\_\_  
 Client: \_\_\_\_\_  
 Company: \_\_\_\_\_  
 Observer: \_\_\_\_\_  
 Note: \_\_\_\_\_

Time of Acquisition  
 Date: \_\_\_\_\_  
 Time: \_\_\_\_\_

Time of Processing  
 Date: \_\_\_\_\_  
 Time: \_\_\_\_\_

Units: meters  
 Sort: As acquired  
 Const: \_\_\_\_\_

Station spacing [m]: 2.0000  
 Min. horizontal separation [%]: 25  
 Profile start offset [m]: 0.0000  
 Left handed coordinates  
 Force grid cell size  
 Cell size [m]: 0.4000

Add borehole lines for WET tomography

Borehole 1 line: Select \_\_\_\_\_  
 Borehole 2 line: Select \_\_\_\_\_  
 Borehole 3 line: Select \_\_\_\_\_  
 Borehole 4 line: Select \_\_\_\_\_

OK Cancel Reset

Fig. 2 : Header|Profile

**Import shots**

Import data type: ASCII column format

Input directory: select one data file. All data files will be imported  
 Select: D:\ray32\P1\_6-7D\INPUT\

Take shot record number from: Record number

Optionally select .HDR batch file and check Batch import  
 .HDR batch: \_\_\_\_\_

Write .HDR batch file listing shots in input directory  
 Output .HDR: \_\_\_\_\_  
 Write .HDR only  Import shots and write .HDR

Overwrite existing shot data:  Overwrite all  Prompt overwriting  Limit offset  
 Batch import

Maximum offset imported [station nos.]: 1000.00

Default shot hole depth [m]: 0.00  
 Default spread type: 10: 360 channels

Target Sample Format: 32-bit floating point

Turn around spread by 180 degrees during import  
 Correct picks for delay time (use e.g. for .PIK files)

Default sample interval [msec]: 0.100000000  
 Default sample count: 900

Import shots Cancel import Reset import

Fig. 3 : File|Import Data

**Edit Surfer plot limits**

Plot Limits  
 Plot limits active

Min. offset: 0.000 [m]  
 Max. offset: 240.000 [m]  
 Min. elevation: 20.000 [m]  
 Max. elevation: 72.000 [m]  
 Min. velocity: 500 [m/sec.]  
 Max. velocity: 6000 [m/sec.]

Plot Scale  
 Proportional XY Scaling  
 Page unit centimeter. Uncheck for inch.  
 X Scale length: 6.000 [inch]  
 Y Scale length: 4.000 [inch]

Color Scale  
 Adapt color scale

Scale height: 1.340 [inch]  
 Velocity interval: 500 [m/sec.]  
 Coverage: 100 [paths/pixel]

OK Cancel Reset Reset to grid

Fig. 4 : Grid|Surfer plot Limits

**WET update weighting**

Parameters for Cosine-Squared weighting function

a : Cosine argument: 0.500 [power]  
 b : Cosine-Squared power: 10.000 [power]

Decrease velocity update in high-coverage areas  
 Decrease update active  
 Velocity update: 0.000 [power]

OK Cancel Reset

Fig. 5 : WET Tomo|WET Update weighting

### Edit WET Wavepath Eikonal Traveltime Tomography Parameters

Specify initial velocity model  
 D:\ray32\P1\_6-7D\gradomo\GRADIENT.GRD

Stop WET inversion after  
 Number of WET tomography iterations :  iterations  
 or RMS error gets below  percent  
 or RMS error does not improve for n =  iterations  
 or WET inversion runs longer than  minutes

WET regularization settings  
 Wavepath frequency :  Hz   
 Ricker differentiation [-1.Gaussian,-2.Cosine]  times  
 Wavepath width [percent of one period] :  percent   
 Wavepath envelope width [% of period] :  percent  
 Min. velocity  Max. velocity  m/sec.  
 Width of Gaussian for one period [sigma] :  sigma

Gradient search method  
 Steepest Descent  Conjugate Gradient

Conjugate Gradient Parameters  
 CG iterations  Line Search iters.   
 Tolerance  Line Search tol.   
 Initial step   Steepest Descent step

### Edit WET Tomography Velocity Smoothing Parameters

Determination of smoothing filter dimensions  
 Full smoothing after each tomography iteration  
 Minimal smoothing after each tomography iteration  
 Manual specification of smoothing filter, see below

Smoothing filter dimensions  
 Half smoothing filter width :  columns  
 Half smoothing filter height :  grid rows

Suppress artefacts below steep topography  
 Adapt shape of filter. Uncheck for better resolution.

Maximum relative velocity update after each iteration  
 Maximum velocity update :  percent

Smooth after each nth iteration only  
 Smooth nth iteration : n =  iterations

Smoothing filter weighting  
 Gaussian  Uniform  No smoothing  
 Used width of Gaussian  sigma  
 Uniform central row weight  [1..100]

Smooth velocity update before updating tomogram  
 Smooth velocity update  Smooth last iteration

Damping of tomogram with previous iteration tomogram  
 Damping   Damp before smoothing

Fig. 6 : WET Tomo|Interactive WET (left) . Edit velocity smoothing (right).

### Edit WET runs - wavepath width

| Run No. | Freq. [Hz]                        | Width [%]                         | Width [ms]                         | Iterations                      |   |
|---------|-----------------------------------|-----------------------------------|------------------------------------|---------------------------------|---|
| Run 1   | <input type="text" value="50.0"/> | <input type="text" value="30.0"/> | <input type="text" value="6.000"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 2   | <input type="text" value="50.0"/> | <input type="text" value="26.0"/> | <input type="text" value="5.200"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 3   | <input type="text" value="50.0"/> | <input type="text" value="22.0"/> | <input type="text" value="4.400"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 4   | <input type="text" value="50.0"/> | <input type="text" value="18.0"/> | <input type="text" value="3.600"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 5   | <input type="text" value="50.0"/> | <input type="text" value="15.0"/> | <input type="text" value="3.000"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 6   | <input type="text" value="50.0"/> | <input type="text" value="12.0"/> | <input type="text" value="2.400"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 7   | <input type="text" value="50.0"/> | <input type="text" value="10.0"/> | <input type="text" value="2.000"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 8   | <input type="text" value="50.0"/> | <input type="text" value="8.0"/>  | <input type="text" value="1.600"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 9   | <input type="text" value="50.0"/> | <input type="text" value="6.0"/>  | <input type="text" value="1.200"/> | <input type="text" value="20"/> | <input type="checkbox"/> Blank            |
| Run 10  | <input type="text" value="50.0"/> | <input type="text" value="5.0"/>  | <input type="text" value="1.000"/> | <input type="text" value="20"/> | <input checked="" type="checkbox"/> Blank |

WET runs active  
 Scale default widths  
 Plot runs in Surfer  
 Prompt run misfit

Runs   
 All runs completed  
 Current run   
 Resume current run

Blank below wavepath envelope  
 Blank after each run  Blank after last run

Fig. 7 : WET Tomo|Interactive WET|Iterate . Edit WET runs for multiscale WET.

P1\_6-7D RMS error 16.3%=4.13ms 1D-Gradient smooth initial model v. 3.36

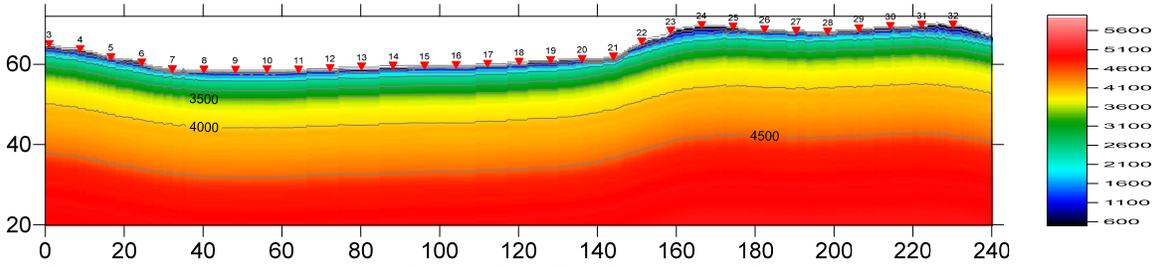


Fig. 8 : Smooth inversion starting model . See Fig. 13/14/15 for  $\Delta t_{atV}$  + XTV Settings & Smooth inversion Settings .

P1\_6-7D initial P1\_6-7\_2018m\_e4.grd v. 3.36

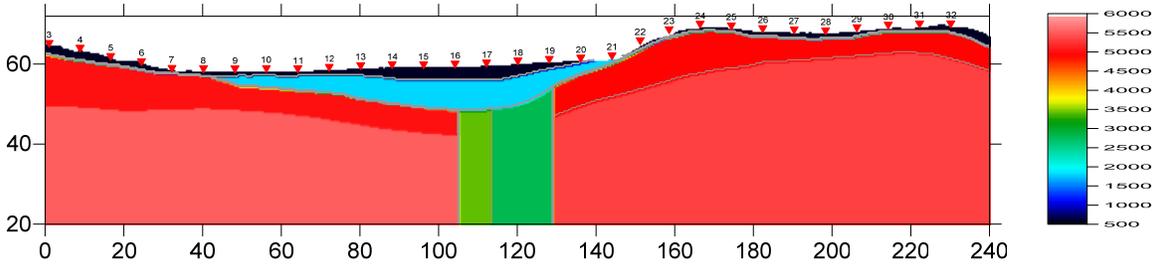


Fig. 9 : true model over which synthetic shots were forward modeled by [NGU](#).

P1\_6-7D RMS error 0.6%=0.15ms 22 WET itr. 50Hz Width 5.0% initial RUN9IT23.GRD v. 3.36

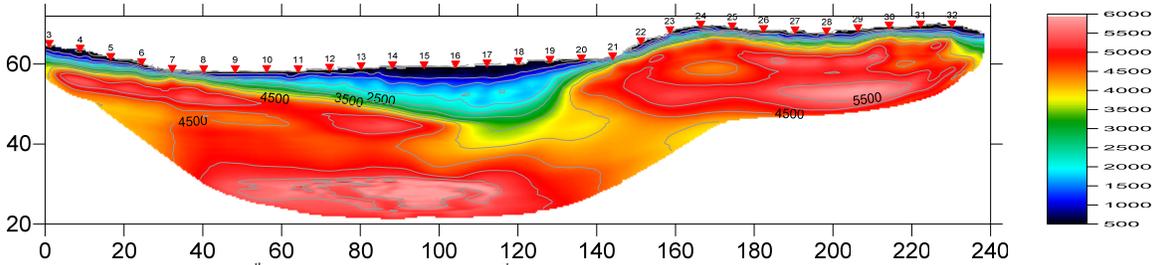


Fig. 10 : WET output of 10<sup>th</sup> run. Starting model for 1<sup>st</sup> run is Fig. 8. See Fig. 1 for misfit. Smooth *n*th iteration = 3.

P1\_6-7D RMS error 1.2%=0.30ms 22 WET itr. 50Hz Width 15.0% initial RUN4IT23.GRD v. 3.36

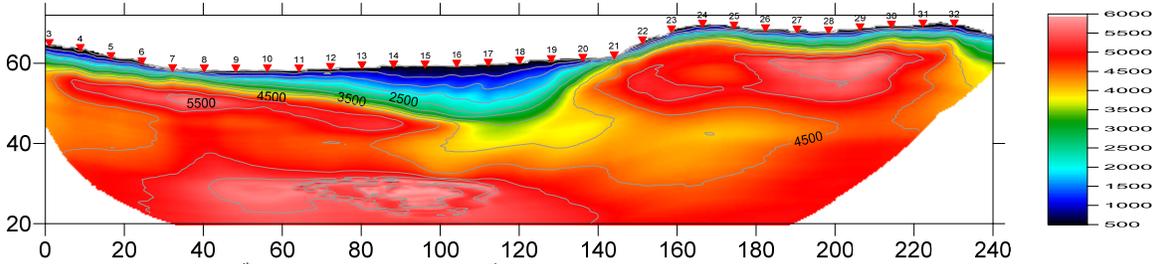


Fig. 11 : WET output of 5<sup>th</sup> run. Starting model for 1<sup>st</sup> run is Fig. 8. Note too wide imaging of fault zone compared to Fig. 9.

P1\_6-7D RMS error 0.6%=0.15ms 22 WET itr. 50Hz Width 5.0% initial RUN9IT23.GRD v. 3.36

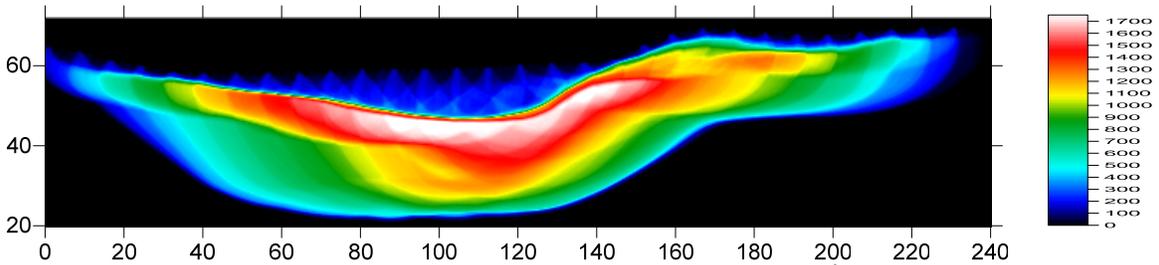


Fig. 12 : Wavepath coverage plot obtained with Fig. 10. Unit is wavepaths per pixel [ $1/m^2$ ] .

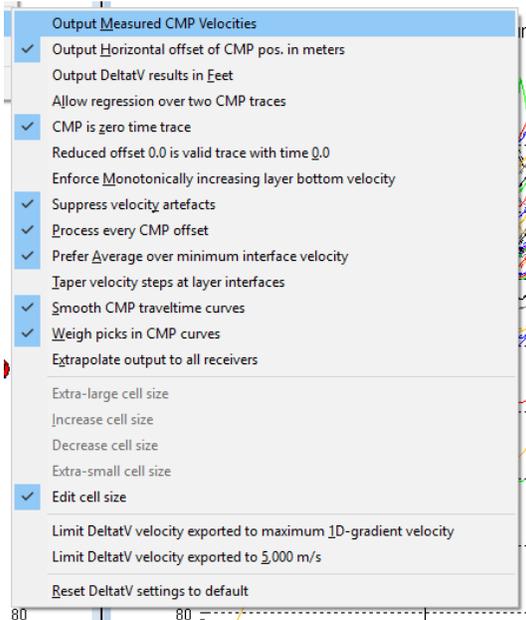


Fig. 13 : *DeltatV/DeltatV Settings*. Check *Suppress velocity artefacts* to enforce continuous CMP sorted traveltimes curves and filter out bad picks from traveltimes curves.

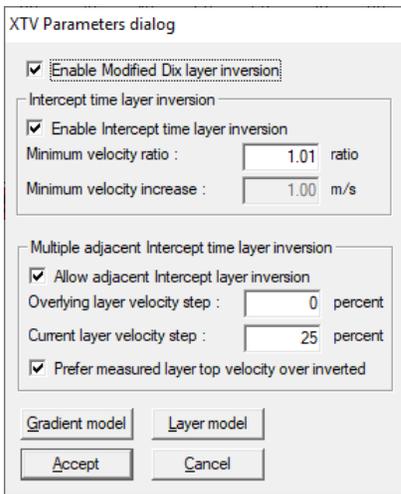


Fig. 14 : edit *XTV parameters*

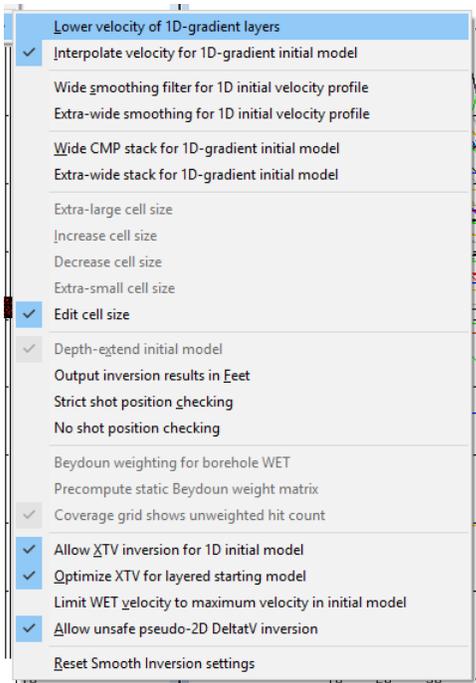


Fig. 15 : edit menu *Smooth invert*|*Smooth inversion Settings*

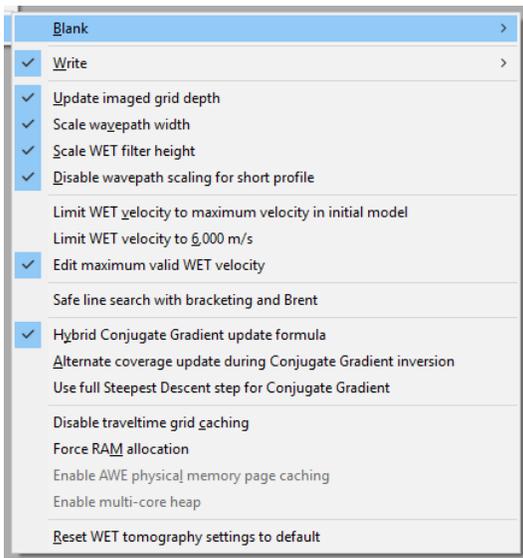


Fig. 16 : edit menu *WET Tomo*|*WET tomography Settings*

To restore database files and result files :

Subdirectories `c:\RAY32\p1_6-71D\GRADTOMO`, `...\INPUT`, `...\seis32_GradTomo_Mar19_2019` and `...\model` are available in this [RAR archive](#). Open the `...\GRADTOMO\WETRUN10\VELOIT23.PAR` file e.g. with Windows Notepad editor to review *WET inversion* parameters used.

Use Rayfract® 3.36 command ***Grid|Reset DeltatV and WET settings to .PAR file...*** with file `...\GRADTOMO\WETRUN10\VELOIT23.GRD` to reset your profile's *DeltatV* and *WET inversion* settings to `...\GRADTOMO\WETRUN10\VELOIT23.PAR`.

Or quit our software via *File|Exit*. In Windows Explorer copy all 34 `seis32.*` database files from directory `...\\seis32_GradTomo_Mar19_2019` into `C:\RAY32\P1_6-7D` directory. Now reopen your profile with *File|Open Profile...* and `C:\RAY32\P1_6-7D\SEIS32.DBD`.

Summary :

NGU 2018 report with Fig. 4.5.2 showing *WET inversion* of above synthetic model data (Fig. 1) using *DeltatV+XTV* pseudo-2D refraction starting model and *Conjugate-gradient single-run WET inversion* is available at [http://www.ngu.no/upload/Publikasjoner/Rapporter/2018/2018\\_015.pdf](http://www.ngu.no/upload/Publikasjoner/Rapporter/2018/2018_015.pdf) .

WET inversion shown in Fig. 10 using 10 WET runs with 7 Conjugate-Gradient iterations each and parameters shown in Fig. 6 and Fig. 7 took about 8 minutes on 2017 Apple iMac. This iMac comes with 2.3 GHz Intel Core i5 processor running 4 OpenMP threads under Windows 10 Pro 64-bit in Parallels Desktop 14 for Mac.

We recommend using our *1D-gradient starting model* with single-run or multirun WET inversion, as described above. Our *DeltatV+XTV starting model* as shown in our [twin tutorial](#) for above data shows strong artefacts which in this case cannot be completely removed by WET inversion. See [Sheehan et al. 2005](#) for an evaluation of our Smooth inversion method using our 1D-gradient starting model.

Multirun WET inversion may not make sense except if you have very accurate first break picks and exact recording geometry. Check traveltimes reciprocity in *Trace|Offset gather*. Also multirun WET inversion requires more time and effort to optimally tune the multirun schedule and WET smoothing.

We recommend using [overlapping receiver spreads](#) and profile-internal far-offset shots to reach deeper and more meaningful imaging of fault zones in basement.

Our Rayfract® software offers multiple interpretation methods and parameters to explore the non-uniqueness of the solution space. It is the user's job to sufficiently explore the solution space with our methods and varying parameters, and to find an appropriate combination of methods and parameters for each individual data set. This choice may be guided by a-priori information e.g. from boreholes or other geophysical methods.

We thank Dr. Georgios Tassis at NGU for making available above report and synthetic data.

For an objective comparison of tomographic refraction analysis methods see [Zelt et al. 2013](#) (JEEG, September 2013, Volume 18, Issue 3, pp. 183–194).

Copyright © 1996-2019 Intelligent Resources Inc. All rights reserved.