

VSP constrained refraction tomography with Rayfract® version 3.35 & 4.01 Oct 2020 :

- Fig. 1 : left : Trace|Offset gather, center : Tace|Shot gather, right : Refractor|Shot breaks. Shows fit between picked times (solid colored curves) and modeled times (dashed colored curves) obtained by forward modeling over Fig. 2.
- File New Profile..., set File name to 11REFR and click Save button
- set Station spacing to 1.0m in Header | Profile.... Set Profile start offset [m] to -28.0.
- set *Cell size* [*m*] to 0.5. Check box *Force grid cell size*.
- unzip 1611 refr.3dd.rar with 1611 refr.3dd.txt in C:\RAY32\11REFR\INPUT
- check *File*|*Import Data*|*Settings*|*Import horizontal borehole survey or .3DD refraction survey* if this option is enabled. Since 2020 version 3.36 you can skip this step.
- check *File*|*Import Data Settings*|*X coordinate is corrected for topography already*
- select File Import Data ... and set Import data type to Tweeton GeoTomCG .3DD
- leave Default spread type at 10: 360 channels. Set Default sample count to 2000.
- click upper Select button, navigate into C:\RAY32\11REFR\INPUT and select file 1611 refr.3dd.txt
- click Open button, Import shots button. The Import shot dialog is shown for each shot in the .3DD file.
- for each shot leave Layout start and Shot pos. at shown values and click Read button
- select Trace|Shot gather, Trace|Offset gather and Window|Tile to obtain Fig. 1
- for each window click title bar, press ALT+P, set Maximum time to 100 ms and hit ENTER key
- for *Trace*|Shot gather & *Trace*|Offset gather click title bar. Uncheck Display|Use red cross for picked first breaks. Check Display|Solid color pick display & Picks always cover traces.
- click title bar of *Refractor*|Shot breaks window. Uncheck Mapping|Display raytraced traveltimes.
- check *Mapping*|Color picked traveltime curves
- uncheck all blanking options in WET Tomo|WET tomography Settings|Blank submenu
- check WET Tomo WET tomography Settings Edit maximum valid WET velocity
- create borehole profile 1611HOLE and import VSP shots as described in tutorial 1611HOLE.pdf
- in *Header* | *Profile* click topmost *Select button* and select C:\RAY32\1611HOLE\SEIS32.DBD. See Fig. 5.
- select Smooth invert|WET with 1D-gradient initial model and confirm for default interpretation
- select *Grid*|*Surfer plot Limits*. Set *X Scale* to 4.5 inch. Click *button Reset to grid* and select C:\ray32\11REFR\GRADTOMO\VELOIT20.GRD. Check box *Plot limits active*.
- set Min. velocity to 200m/s and Max. velocity to 5000m/s. Click OK button.

LINE 11 RMS error 5.0%=4.32ms initial GRADIENT.GRD Version 3.35



Fig. 2a : 1D-gradient starting model, obtained by horizontally averaging DeltatV inversion output. Default Smooth inversion settings, default DeltatV settings.

LINE 11 RMS error 2.1%=1.85ms 100 WET iters. 50Hz Width 19.0% initial GRADIENT.GRD Version 3.35



Fig. 2b : Tomogram with 1D-gradient starting model Fig. 2a, 100 Steepest Descent WET iterations, default WET settings. Wavepath width 19%, Max. velocity 4,500 m/s. WET settings as in Fig. 4.

- set WET Tomo|Interactive WET tomography|Number of iterations to 100. Set Wavepath width to 19% and Max. velocity to 4500m/s. See Fig. 4. Click Start tomography processing to obtain Fig. 2 & 3.
- for WET parameters used see archive <u>GRAD335 Width19% 100Iters.rar</u> with starting model files GRADIENT.GRD & GRADIENT.PAR, VELOIT100.GRD & .PAR and .SRF Surfer 11 plots
- click *WET Tomo*|*Interactive WET tomography*|*Iterate* and specify multiscale tomography parameters as shown in Fig. 6
- check box WET runs active, click OK button and Start tomography processing button for Fig. 7 & 8

For help on *WET inversion* parameters see <u>.pdf reference</u> chapter *WET Wavepath Eikonal Traveltime tomography*.



LINE 11 RMS error 2.1%=1.85ms 100 WET iters. 50Hz Width 19.0% initial GRADIENT.GRD Version 3.35

Fig. 3 : WET wavepath coverage plot obtained with Fig. 2b. Shows number of wavepaths per pixel.

Edit WET Wavepath Eikonal Traveltime Tomography Parameters	Edit WET Tomography Velocity Smoothing Parameters		
Specify initial velocity model	Determination of smoothing filter dimensions		
Select D:\RAY32\11REFR\GRADTOMO\GRADIENT.GRD	Full smoothing after each tomography iteration		
Stop WET inversion after	 Minimal smoothing after each tomography iteration 		
Number of WET tomography iterations : 100 iterations	 Manual specification of smoothing filter, see below 		
or RMS error gets below 2.0 percent	Smoothing filter dimensions		
or PMS error does not improve for n = 50 iterations	Half smoothing filter width : 2 columns		
	Half smoothing filter height : 1 grid rows		
or WEI inversion runs longer than 100 minutes	Filter shallow disping we want attracts from model		
WET regularization settings			
Wavepath frequency : 50 Hz Iterate	Automatically adapt shape of rectangular filter matrix		
Ricker differentiation [-1 is Gaussian bell] : -1 times	Maximum relative velocity update after each iteration		
Wavepath width [percent of one period] : 19.0 percent Iterate	Maximum velocity update : 25 percent		
Wavepath envelope width [% of period] : 0.0 percent	Smooth after each nth iteration only		
Min. velocity : 10 Max. velocity : 4500 m/sec.	Smooth nth iteration : n = 1 iterations		
Width of Gaussian for one period [sigma]: 3.0 sigma	Smoothing filter weighting		
	C Gaussian		
Gradient search method G Steepest Descent C Conjugate Gradient	Used width of Gaussian 1.0 sigma		
- Conjugate Gradient Parameters	Uniform central row weight 1.0 [1100]		
	Smooth velocity update before updating tomogram		
Initial step 0.10 Line Search iters. 3	Smooth velocity update Smooth last iteration		
Steepest Descent step CG iterations 15	Damping of tomogram with previous iteration tomogram		
Edit <u>v</u> elocity smoothing Edit grid file generation	Damping [01] 0.000 Damp before smoothing		
Start tomography processing Reset Cancel	Accept parameters Reset parameters		

Fig. 4 : WET parameter settings for Fig. 2 & 3. left : main interactive WET dialog. right : edit velocity smoothing

Edit Profile			
Line ID Line type Job ID	LINE 11 Time of Acquisition Refraction spread/line Date Itest refraction & borehole line Time		
Instrument	unknown Time of Processing	_	
Client Company	Date Time		
Observer Note	Units meters Sort As acquired	• •	
Hole	✓ Const		
Station spacin	g [m] 1.0000 Left handed coordinates		
Min. horizonta	separation [%] 25 🔽 Force grid cell size		
Profile start of	iset [m] -28.0000 Cell size [m] 0.50	00	
Add borehol	e lines for WET tomography		
Borehole 1 lin	e Select D:\ray32\1611HOLE\SEIS32.D	BD	
Borehole 2 lin	e Select		
Borehole 3 lin	e Select		
Borehole 4 lin	e Select		
ОК	Cancel Reset		

Fig. 5 : Header|Profile dialog. Easily add borehole line(s) with Select button(s).

Edit WET ru	ins - wavep	ath width				-
Run No.	Freq. [Hz]	Width [%]	Width [ms]	Iterations	Dirak.	ОК
Run 1 Run 2	50.0	26.0	5.200	20	Blank	Cancel
Run 3	50.0	23.0	4.600	20	Blank	Reset
Run 4	50.0	20.0	4.000	20	Blank	WET runs active
Run 5	50.0	18.0	3.600	20	Blank	Scale default widths
Run 6	50.0	16.0	3.200	20	Blank	Plot runs in Suffer
Run 7	50.0	13.0	2.600	20	Blank	Runs completed 8
Run 8	50.0	10.0	2.000	20	Blank	All runs completed
Run 9	50.0	2.0	0.400	0	Blank	Current run no.
Run 10	50.0	1.0	0.200	0	Blank	Resume current run
Blank below wavepath envelope Blank after each run Blank after last run						

Fig. 6 : WET Tomo|Interactive WET tomography|Iterate . Specify parameters for multiscale tomography.



LINE 11 RMS error 2.0%=1.75ms 20 WET iters. 50Hz Width 10.0% initial RUN7IT20.GRD Version 3.35

Fig. 7 : multiscale tomography obtained with multirun WET parameters shown in Fig. 6



LINE 11 RMS error 2.0%=1.75ms 20 WET iters. 50Hz Width 10.0% initial RUN7IT20.GRD Version 3.35

Fig. 8 : WET wavepath coverage plot obtained with Fig. 7. Unit is wavepaths per pixel.

Note the improved vertical resolution at top of basement in Fig. 7 showing <u>multiscale tomography</u> when compared to Fig. 2b showing single-run WET inversion.

WETRUN8 Gradient Start.rar contains files for Fig. 7. WETRUN8 ConstVelo Start.rar contains the same files obtained with *constant-velocity starting model*. See WETRUN1 Gradient Start.rar and WETRUN1 ConstVelo Start.rar for starting models and tomograms obtained with first WET run.

Since Oct 2020 our latest software version 4.01 allows WDVS Wavelength-Dependent Velocity Smoothing (<u>Zelt and Chen 2016</u>). In Fig. 9&10 we show 200 Steepest-Descent WET iterations (Fig. 12) with Plus-Minus method starting model (Fig. 11) and WDVS enabled with *WDVS frequency* 200Hz, *Angle increment* 7 degrees and *Regard nth node* = 3 (Fig. 13). Note the *minimized WET smoothing* settings in Fig. 12. We can reduce WET smoothing this much since we enabled *WDVS smoothing* see Fig. 13.





Fig. 9 : Single-run Steepest Descent WET inversion. 200 WET iterations, wavepath width 9% (Fig. 12). Plus-Minus starting model (Fig. 11). WDVS frequency 200Hz, Angle increment 7 degrees, Regard nth node = 3 (Fig. 13).

-200

100 -0



ό Fig. 10 : WET wavepath coverage obtained with Fig. 9

370-

-30

-20

-10

LINE 11 RMS error 36.7%=12.51ms Plus-Minus method initial PLUSMODL.GRD version 3.36 -27 -20 -13 -6 8 15 22 29 36 1 43

10

20

40

30



Fig. 11 : Plus-Minus method starting model used for Fig. 9 and Fig. 10

In Fig. 11 we show the Plus-Minus method starting model used to obtain Fig. 9 & 10. We forced the *grid cell size* to 1.0m in *Header*|*Profile* to speed up WDVS velocity smoothing. In Fig. 12 we show interactive WET settings used for Fig. 9. In Fig. 13 we show WDVS settings for Fig. 9.

Edit WET Wavepath Eikonal Traveltime Tomograph	ny Parameters	Edit WET Tomography Velocity Smoothing Parameters		
Specify initial velocity model	Determination of smoothing filter dimensions			
Select D:\ray32\11R	C Full smoothing after each tomography iteration			
Stop WET inversion after	 Minimal smoothing after each tomography iteration 			
Number of WET tomography iterations :	200 iterations	Manual specification of smoothing filter, see below		
or RMS error gets below	20 percent	Smoothing filter dimensions		
	20 iterations	Half smoothing filter width : 3 columns		
j or RMS error does not improve for n =	20 iterations	Half smoothing filter height : 1 grid rows		
or WET inversion runs longer than	100 minutes			
WET regularization settings		Suppress artefacts below steep topography		
Wavepath frequency :	50 Hz Iterate	Adapt shape of filter. Uncheck for better resolution.		
Ricker differentiation [-1:Gaussian,-2:Cosine] :	-1 times	Maximum relative velocity update after each iteration		
Wavepath width [percent of one period] :	9.0 percent Iterate	Maximum velocity update : 25.00 percent		
Wavepath envelope width [% of period] : 0.0 percent		Smooth after each nth iteration only		
Min. velocity : 10 Max. velocity :	6000 m/sec.	Smooth nth iteration : n = 50 iterations		
Width of Gaussian for one period [sigma]:	3.0 sigma	Smoothing filter weighting		
Gradient search method	C Gaussian			
Steepest Descent	Used width of Gaussian 2.0 sigma			
Conjugate Gradient Parameters	Uniform central row weight 100.0 [1100]			
CG iterations 10 Line Sear	Smooth velocity update before updating tomogram			
Tolerance 0.001 Line Search tol. 0.0010		Smooth update Smooth nth 🔽 Smooth last		
Initial step 0.10	Damping of tomogram with previous iteration tomogram			
Edit velocity smoothing Edit	Damping [01] 0.000 Damp before smoothing			
Start tomography processing	Accept parameters Reset parameters			

Fig. 12 : WET Tomo|Interactive WET settings used for Fig. 9. Note the minimized WET smoothing settings. We can reduce WET smoothing this much since we enabled WDVS smoothing see Fig. 13.

Edit WDVS (Zelt & Chen 2016)				
Edit parameters for wavelength-dependent velocity smoothing				
use WDVS for forward mo	✓ use WDVS for forward modeling of traveltimes			
WDVS frequency	200	[Hz]		
Angle increment	7	[Degree]		
Regard nth node	3	[node]		
Parameters for Cosine-Squared weighting function				
a : Cosine argument power	1.000	[power]		
b : Cosine-Squared power	1.000	[power]		
OK Cance	I Res	et		

Fig. 13 : WDVS settings used for Fig. 9. WDVS frequency 200Hz. Angle increment 7 degrees. Regard nth node = 3.

With WDVS enabled (Fig. 13) we can *minimize WET smoothing* (Fig. 12) and still get robust WET inversion output (Fig. 9 & 10). WDVS is described in Zelt, C. A. and J. Chen, Frequency-dependent traveltime tomography for near-surface seismic refraction data, Geophys. J. Int., 207, 72-88, 2016.

11REFR LAYRTOMO Oct24 2020.rar contains Surfer 11 files for Fig. 9.

11REFR seis32 LayrTomo Oct24 2020.rar contains profile database files for Fig. 9.

Next we disregard VSP shots and invert first break picks for refraction shots only :

- select *Header* | *Profile* (Fig. 5). Click *Reset* to delete all borehole line selections. Click *button OK*.
- select Smooth invert|Custom 1D-gradient velocity profile
- click button Reset limits to grid and select C:\ray32\11REFR\GRADTOMO\VELOIT100.GRD
- check *box Force grid limits* and click *button OK*

LINE 11 RMS error 1.8%=1.56ms 100 WET iters. 50Hz Width 19.0% initial GRADIENT.GRD Version 3.35





LINE 11 RMS error 1.8%=1.56ms 100 WET iters. 50Hz Width 19.0% initial GRADIENT.GRD Version 3.35

Fig. 15 : Wavepath coverage plot obtained with Fig. 9. Unit is wavepaths per pixel.

• select Smooth invert | WET with 1D-gradient initial model and confirm for default interpretation

- set WET Tomo|Interactive WET tomography|Number of iterations to 100. See Fig. 4.
- set *Wavepath width* to 19% and *Max. velocity* to 4500m/s. See Fig. 4.
- click Iterate and uncheck WET runs active. Click OK and Start tomography processing for Fig. 9&10.

Note the limited depth penetration in Fig. 14&15 due to the shallow high-velocity layer at elevation 425m and lower-velocity region below this layer. Classic refraction theory states that you cannot image below a velocity inversion. As shown we still get a meaningful estimate of top of bedrock with *WET inversion*.

Copyright© 1996-2021 Intelligent Resources Inc. All rights reserved.